## Relation between Ideal convergence and Sequence selection principle

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Diagram. Scheepers' diagram.



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#### Covering and ideals

- The family  $\mathcal{I} \subseteq \mathcal{P}(\omega)$  is called **ideal**, if
  - it is closed under taking subsets and finite unions
  - does not contain the set  $\omega$ , but contains all finite subsets of  $\omega$ .
- E.g.: the Frechét ideal, denoted as Fin, is a set  $[\omega]^{<\aleph_0}$ .
- For  $\mathcal{A} \subseteq \mathcal{P}(M)$  we denote  $\mathcal{A}^d = \{A \subseteq M; \ M \setminus A \in \mathcal{A}\}.$

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- the sequence  $\langle U_n: n \in \omega \rangle$  of subsets of X is called an  $\omega$ -cover, if for every  $n \in \omega, U_n \neq X$  and for every finite  $F \subseteq X$  there is n such that  $F \subseteq U_n$ , see [7].
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- the sequence  $\langle U_n : n \in \omega \rangle$  of subsets of X is called  $\gamma$ -cover if for every  $n \in \omega, U_n \neq X$  and for every  $x \in X$ , the set  $\{n \in \omega : x \notin U_n\}$  is finite, see [7].
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  - $\mathcal{I}$ - $\Gamma$  denotes the family of all open  $\mathcal{I}$ - $\gamma$ -covers of X.
  - Fin- $\Gamma = \Gamma$ .

• A sequence  $\langle x_n : n \in \omega \rangle$  elements of a topological space X is  $\mathcal{I}$ -convergent to  $x \in X$  if the set  $\{n \in \omega : x_n \notin U\} \in \mathcal{I}$  for each neighborhood U of x, (written  $x_n \xrightarrow{\mathcal{I}} x$ ).

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- C<sub>p</sub>(X) denotes the set of all continuous functions on X.
  - It can be equipped with inherited topology from Tychonoff product topology of <sup>X</sup>R, i.e., topology of pointwise convergence.
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- $f_n \xrightarrow{\mathcal{I}} f \Leftrightarrow \{n \in \omega : |f_n(x) f(x)| \ge \varepsilon\} \in \mathcal{I} \text{ for each } x \in X \text{ and for each } \varepsilon > 0.$

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- The sequence (f<sub>n</sub>: n ∈ ω) is called *I*-quasi-normal convergent to f on X if there exists a sequence of positive reals (ε<sub>n</sub>: n ∈ ω) and ε<sub>n</sub> <sup>*I*</sup>→ 0 such that {n ∈ ω : |f<sub>n</sub>(x) f(x)| ≥ ε<sub>n</sub>} ∈ *I* for any x ∈ X, denoted f<sub>n</sub> <sup>*I*</sup>→ f. (ε<sub>n</sub>: n ∈ ω) is called control sequence

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- especially, if control sequence is  $\langle 2^{-n} : n \in \omega \rangle$  we are talking about strongly  $\mathcal{I}$ -quasi normal convergence of  $f_n$  to f, written  $f_n \xrightarrow{s\mathcal{IQN}} f$ .

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$$\Omega_x(X) = \left\{ A \in {}^{\omega}(X \setminus \{x\}) : x \in \overline{\{y : (\exists n \in \omega) \ A(n) = y\}} \right\}.$$

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- We use  $\Gamma_0$  instead of  $\operatorname{Fin}$ - $\Gamma_0$ .

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Let  $\mathcal{I}, \mathcal{J}$  be ideals on  $\omega$ . Then  $S_1(\mathcal{I}-\Gamma_0, \mathcal{J}-\Gamma_0)$  can be imagined by follow way

#### Observation

- (1) If X is an  $S_1(\Gamma, \mathcal{J} \cdot \Gamma)$ -space then X is an  $S_1(\Gamma, \Omega)$ -space.
- (2) If  $C_p(X)$  is an  $S_1(\Gamma_0, \mathcal{J} \Gamma_0)$ -space then  $C_p(X)$  is an  $S_1(\Gamma_0, \Omega_0)$ -space.

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## Proposition (V.Š., J.Šupina)

- Let X be a topological space. Then
- (1) X is an  $S_1(\mathcal{I}-\Gamma,\Gamma)$ -space if and only if X has  $\begin{bmatrix} \mathcal{I}-\Gamma\\ \Gamma \end{bmatrix}$  and  $S_1(\Gamma,\Gamma)$ .
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### Lemma (V.Š., J.Šupina)

- (1) For any countable  $\omega$ -cover  $\mathcal{U}$  of X and its bijective enumeration  $\langle U_n : n \in \omega \rangle$  there is an ideal  $\mathcal{I}$  such that  $\langle U_n : n \in \omega \rangle$  is an  $\mathcal{I}$ - $\gamma$ -cover.
- (2) For any countable family of functions  $\mathcal{E}$  on X such that  $\mathbf{0} \in \overline{\mathcal{E} \setminus \{\mathbf{0}\}}$  and its bijective enumeration  $\langle f_n : n \in \omega \rangle$  there is an ideal  $\mathcal{I}$  such that  $f_n \xrightarrow{\mathcal{I}} \mathbf{0}$ .

## Covering $\mathrm{S}_1(\mathcal{P},\mathcal{R})$ and $\mathrm{S}_1(\mathcal{P},\mathcal{R})$ for functions

Let us recall a folklore result by J. Gerlits and Zs. Nagy [4] for a Tychonoff space X:  $X \operatorname{has} {\Omega \choose \Gamma} \Leftrightarrow X \operatorname{has} S_1(\Omega, \Gamma) \Leftrightarrow C_p(X) \operatorname{has} {\Omega_0 \choose \Gamma_0} \Leftrightarrow C_p(X) \operatorname{has} S_1(\Omega_0, \Gamma_0).$ 

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## Theorem (V.Š., J.Šupina)

Let X be a Tychonoff topological space. The following statements are equivalent.

- (a) X is an  $S_1(\Omega, \Gamma)$ -space.
- (b) X is an  $S_1(\mathcal{I}-\Gamma,\Gamma)$ -space for every ideal  $\mathcal{I}$ .
- (c)  $C_p(X)$  is an  $S_1(\mathcal{I}-\Gamma_0,\Gamma_0)$ -space for every ideal  $\mathcal{I}$ .
- (d) X has  $\begin{bmatrix} \mathcal{I} \Gamma \\ \Gamma \end{bmatrix}$  for every ideal  $\mathcal{I}$ .
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- (d) X has  $\begin{bmatrix} \mathcal{I} \cdot \Gamma \\ \Gamma \end{bmatrix}$  for every ideal  $\mathcal{I}$ .
- (e)  $C_p(X)$  has  $\begin{bmatrix} \mathcal{I} \Gamma_0 \\ \Gamma_0 \end{bmatrix}$  for every ideal  $\mathcal{I}$ .

$$\begin{array}{c} \mathbf{S}_{1}(\Gamma,\Gamma) & \longrightarrow \mathbf{S}_{1}(\Gamma,\mathcal{J}\Gamma) & \longrightarrow \mathbf{S}_{1}(\Gamma,\Omega) \\ \uparrow & \uparrow \\ \mathbf{S}_{1}(\mathcal{I}\Gamma,\Gamma) & \longrightarrow \mathbf{S}_{1}(\mathcal{I}\Gamma,\mathcal{J}\Gamma) \\ \uparrow \\ \mathbf{S}_{1}(\Omega,\Gamma) \end{array}$$

Diagram. Covering selection principles.

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$$\begin{array}{c} \mathrm{S}_{1}(\Gamma_{0},\Gamma_{0}) \longrightarrow \mathrm{S}_{1}(\Gamma_{0},\mathcal{J}\text{-}\Gamma_{0}) \longrightarrow \mathrm{S}_{1}(\Gamma_{0},\Omega_{0}) \longrightarrow \mathsf{Ind}_{\mathbb{Z}}(X) = 0 \\ \uparrow & \uparrow \\ \mathrm{S}_{1}(\mathcal{I}\text{-}\Gamma_{0},\Gamma_{0}) \longrightarrow \mathrm{S}_{1}(\mathcal{I}\text{-}\Gamma_{0},\mathcal{J}\text{-}\Gamma_{0}) \\ \uparrow \\ \mathrm{Fréchet} \end{array}$$

Diagram. Selection principles for functions.

• We say that a sequence  $\langle f_n : n \in \omega \rangle$  is monotone sequence if for any  $n \in \omega$ and  $x \in X$  we have  $f_n(x) \ge f_{n+1}(x)$ .

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- $\mathcal{I}$ - $\Gamma_{\mathbf{0}}^{m} = \{A \in {}^{\omega}(\mathcal{C}_{p}(X) \setminus \{\mathbf{0}\}): A \text{ is } \mathcal{I}\text{-monotone and } \mathcal{I}\text{-convergent to } \mathbf{0}\}.$

## Monotonne version of $S_1(\mathcal{P}, \mathcal{R})$ for functions

- We say that a sequence ⟨f<sub>n</sub> : n ∈ ω⟩ is monotone sequence if for any n ∈ ω and x ∈ X we have f<sub>n</sub>(x) ≥ f<sub>n+1</sub>(x).
- $\Gamma_{\mathbf{0}}^m = \{A \in {}^{\omega}(\mathcal{C}_p(X) \setminus \{\mathbf{0}\}) : A \text{ is monotone and convergent to } \mathbf{0}\}.$
- We say that a sequence  $\langle f_n : n \in \omega \rangle$  is  $\mathcal{I}$ -monotone sequence if  $\{n : f_n \nleq f_m\} \in \mathcal{I}$  for every  $m \in \omega$ .
- $\mathcal{I}$ - $\Gamma_{\mathbf{0}}^{m} = \{A \in {}^{\omega}(\mathcal{C}_{p}(X) \setminus \{\mathbf{0}\}): A \text{ is } \mathcal{I}\text{-monotone and } \mathcal{I}\text{-convergent to } \mathbf{0}\}.$

## Lemma (V.Š., J.Šupina)

- (1)  $C_p(X)$  has the property  $S_1(\Gamma_0^m, \mathcal{J} \Gamma_0)$  if and only if  $C_p(X)$  has the property  $S_1(\operatorname{Fin} \Gamma_0^m, \mathcal{J} \Gamma_0)$ .
- (2)  $C_p(X)$  has the property  $\begin{bmatrix} \Gamma_0^m \\ \mathcal{J}QN_0 \end{bmatrix}$  if and only if  $C_p(X)$  has the property  $\begin{bmatrix} \operatorname{Fin} \Gamma_0^m \\ \mathcal{J}QN_0 \end{bmatrix}$ .
- (3)  $C_p(X)$  has the property  $\begin{bmatrix} \Gamma_0^m \\ s \mathcal{J} Q N_0 \end{bmatrix}$  if and only if  $C_p(X)$  has the property  $\begin{bmatrix} \operatorname{Fin} \Gamma_0^m \\ s \mathcal{J} Q N_0 \end{bmatrix}$ .

- We say that a sequence  $\langle f_n : n \in \omega \rangle$  is monotone sequence if for any  $n \in \omega$ and  $x \in X$  we have  $f_n(x) \ge f_{n+1}(x)$ .
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- $\mathcal{I}$ - $\Gamma_{\mathbf{0}}^{m} = \{A \in {}^{\omega}(\mathcal{C}_{p}(X) \setminus \{\mathbf{0}\}): A \text{ is } \mathcal{I}\text{-monotone and } \mathcal{I}\text{-convergent to } \mathbf{0}\}.$

 $S_1(\Gamma_0^m,\Gamma_0) \to S_1(\Gamma_0^m,\mathcal{J}-\Gamma_0)$ 

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 $S_1(\Gamma_0^m,\Gamma_0) \to S_1(\Gamma_0^m,\mathcal{J}-\Gamma_0)$ 

 $S_1(\mathcal{I}\text{-}\Gamma_0,\mathcal{J}\text{-}\Gamma_0) \to S_1(\mathcal{I}\text{-}\Gamma_0^m,\mathcal{J}\text{-}\Gamma_0)$ 

• We say that a topological space X has  $\mathcal{J}$ -Hurewicz property if for each sequence  $\langle \mathcal{U}_n: n \in \omega \rangle$  of open covers of X there are finite  $\mathcal{V}_n \subset \mathcal{U}_n$ ,  $n \in \omega$  such that for each  $x \in X$ ,  $\{n \in \omega: x \notin \bigcup \mathcal{V}_n\} \in \mathcal{J}$ .[3].

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- P. Szewczak and B. Tsaban [10] showed

 $\mathsf{Hurewicz} \longrightarrow \mathcal{J}\text{-}\mathsf{Hurewicz} \longrightarrow \mathsf{Menger}.$ 

### Conection between coverings and functions

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### Proposition (V.Š., J.Šupina)

If X is a perfectly normal topological space then the following are equivalent. Moreover, if X is arbitrary topological space then  $(a) \equiv (b)$ .

- (a)  $C_p(X)$  has  $\begin{bmatrix} \Gamma_0^m \\ s \mathcal{J} Q N_0 \end{bmatrix}$ .
- (b)  $C_p(X)$  has the property  $S_1(\Gamma_0^m, \mathcal{J} \Gamma_0)$ .
- (c) X possesses a  $\mathcal{J}$ -Hurewicz property.

- We say that a topological space X has J-Hurewicz property if for each sequence ⟨U<sub>n</sub>: n ∈ ω⟩ of open covers of X there are finite V<sub>n</sub> ⊂ U<sub>n</sub>, n ∈ ω such that for each x ∈ X, {n ∈ ω : x ∉ ∪ V<sub>n</sub>} ∈ J.[3].
- P. Szewczak and B. Tsaban [10] showed

Hurewicz 
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-Hurewicz  $\longrightarrow$  Menger.

$$\begin{array}{rcl} \mathsf{Hurewicz} & \equiv & \mathrm{S}_{1}(\Gamma_{\mathbf{0}}^{\mathrm{m}},\Gamma_{\mathbf{0}}) & \longrightarrow \mathrm{S}_{1}(\Gamma_{\mathbf{0}}^{\mathrm{m}},\mathcal{J}\text{-}\Gamma_{\mathbf{0}}) & \longrightarrow & \mathsf{Menger} \\ & & & \uparrow & & \uparrow \\ & & & & \uparrow & & \\ & & & \mathrm{S}_{1}(\mathcal{I}\text{-}\Gamma_{\mathbf{0}}^{\mathrm{m}},\Gamma_{\mathbf{0}}) & \longrightarrow & \mathrm{S}_{1}(\mathcal{I}\text{-}\Gamma_{\mathbf{0}}^{\mathrm{m}},\mathcal{J}\text{-}\Gamma_{\mathbf{0}}) \\ & & & & \uparrow & \\ & & & & \mathrm{S}_{1}(\mathcal{I}\text{-}\Gamma_{\mathbf{0}},\Gamma_{\mathbf{0}}) \end{array}$$

Diagram. Monotonic selection principles for functions.

### Theorem (L. Bukovský, P. Das, J.Šupina.[1])

Let  $\mathcal{I}$ ,  $\mathcal{J}$  be ideals on  $\omega$ . If X is a normal topological space then the following are equivalent.

Moreover, the equivalence  $(a) \equiv (b)$  holds for arbitrary topological space X.

- (a)  $C_p(X)$  has  $\begin{bmatrix} \mathcal{I} \Gamma_0 \\ s \mathcal{J} Q N_0 \end{bmatrix}$ .
- (b)  $C_p(X)$  is an  $S_1(\mathcal{I}-\Gamma_0, \mathcal{J}-\Gamma_0)$ -space.
- (c) X is an  $S_1(\mathcal{I}-\Gamma^{sh}, \mathcal{J}-\Gamma)$ -space.

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- (c) X is an  $S_1(\mathcal{I}-\Gamma^{sh}, \mathcal{J}-\Gamma)$ -space.
  - As a corollary L. Bukovský, P. Das and J. Š. obtained the ideal version of Scheepers' result [9].

 $S_1(\mathcal{I}\text{-}\Gamma, \mathcal{J}\text{-}\Gamma) \to S_1(\mathcal{I}\text{-}\Gamma^{sh}, \mathcal{J}\text{-}\Gamma) \Leftrightarrow S_1(\mathcal{I}\text{-}\Gamma_0, \mathcal{J}\text{-}\Gamma_0) \to S_1(\mathcal{I}\text{-}\Gamma_0^m, \mathcal{J}\text{-}\Gamma_0).$ 

#### Conection between coverings and functions



Diagram. The overall relations of investigated properties.

Let  $\mathcal{A} \subseteq \mathcal{P}(\omega)$ .

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  - We say that  $\varphi$  goes through  $\mathcal{I}$ -slalom instead of  $\varphi$  Fin-goes through  $\mathcal{I}$ -slalom.

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 $\mathfrak{b} = \min\left\{ |\mathcal{R}|: \ \mathcal{R} \subseteq {}^{\omega}\omega, \ (\forall \text{Fin-slalom } s)(\exists \varphi \in \mathcal{R}) \ \neg(\varphi \text{ goes through } s) \right\}.$ 

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 $\lambda(\mathcal{I},\mathcal{J}) = \min\left\{ |\mathcal{R}|: \mathcal{R} \text{ contains } \mathcal{I}^d \text{-slaloms, } (\forall \varphi \in {}^\omega \omega) (\exists s \in \mathcal{R}) \neg (\varphi \mathcal{J} \text{-goes through } s) \right\}$ 

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 $\operatorname{cov}^{*}(\mathcal{I}) = \min\left\{ |\mathcal{A}|: \ \mathcal{A} \subseteq \mathcal{I} \land (\forall S \in [\omega]^{\omega}) (\exists A \in \mathcal{A}) \ |S \cap A| = \omega \right\}.$ 

Let  $\mathcal{A} \subseteq \mathcal{P}(\omega)$ .

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 $\mathfrak{k}_{\mathcal{I},\mathcal{J}} = \min\left\{ |\mathcal{A}| : \mathcal{A} \subseteq \mathcal{I} \land \mathcal{A} \not\leq_K \mathcal{J} \right\}.$ 

### Cardinal invariants

• J. Šupina's results [12]:  $\lambda(\operatorname{Fin}, \mathcal{J}) = \mathfrak{b}_{\mathcal{J}}$  and if  $\mathcal{I}_1 \leq_K \mathcal{I}_2$  and  $\mathcal{J}_1 \leq_{KB} \mathcal{J}_2$  then  $\lambda(\mathcal{I}_2, \mathcal{J}_1) \leq \lambda(\mathcal{I}_1, \mathcal{J}_2)$ .

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### Theorem (V.Š., J.Šupina)

- (1) If  $\mathcal{I} \not\leq_K \mathcal{J}$  then  $\lambda(\mathcal{I}, \mathcal{J}) \leq \min\{\mathfrak{k}_{\mathcal{I}, \mathcal{J}}, \mathfrak{b}_{\mathcal{J}}\}.$
- (2) If  $\mathcal{I} \not\leq_K \mathcal{J}$  and  $\mathcal{J} \leq_K \mathcal{I}$  then  $\lambda(\mathcal{I}, \mathcal{J}) = \min\{\mathfrak{k}_{\mathcal{I}, \mathcal{J}}, \lambda(\mathcal{J}, \mathcal{J})\}.$
- (3) If  $\mathcal{I}$  is tall then  $\lambda(\mathcal{I}, \operatorname{Fin}) = \min\{\operatorname{cov}^*(\mathcal{I}), \mathfrak{b}\}.$

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**Diagram**. Cardinal  $\lambda(\mathcal{I}, \mathcal{J})$ .

### Theorem (V.Š., J.Šupina)

Let  $\mathcal{I}, \mathcal{J}$  be ideals on  $\omega, D$  being a discrete topological space. Then the following statements are equivalent.

- (a) D is an  $S_1(\mathcal{I}-\Gamma, \mathcal{J}-\Gamma)$ -space.
- (b)  $C_p(D)$  has  $\begin{bmatrix} \mathcal{I} \Gamma_0 \\ s \mathcal{J} Q N_0 \end{bmatrix}$ .
- (c)  $C_p(D)$  has the property  $S_1(\mathcal{I}$ - $\Gamma_0, \mathcal{J}$ - $\Gamma_0)$
- (d)  $C_p(D)$  has the property  $S_1(\mathcal{I}\text{-}\Gamma_0^m, \mathcal{J}\text{-}\Gamma_0)$ .
- (e)  $|D| < \lambda(\mathcal{I}, \mathcal{J}).$

### Theorem (A. Kwela–M. Repický)

Let D be a discrete topological space. Then the following statements are equivalent.

- (a)  $|D| < \operatorname{cov}^*(\mathcal{I}).$
- (b)  $C_p(D)$  has  $\begin{bmatrix} \mathcal{I}QN_0 \\ QN_0 \end{bmatrix}$ .
- (c)  $C_p(D)$  has  $\begin{bmatrix} \mathcal{I} \Gamma_0 \\ \Gamma_0 \end{bmatrix}$ .
- (d) *D* has the property  $\begin{bmatrix} \mathcal{I} \Gamma \\ \Gamma \end{bmatrix}$ .

• Let  $\mathcal{I}, \mathcal{J} \subseteq \mathcal{P}(\omega)$  be ideals.

(1)  $\operatorname{non}(S_1(\mathcal{I}-\Gamma_0, \mathcal{J}-\Gamma_0)) = \operatorname{non}(S_1(\mathcal{I}-\Gamma_0^m, \mathcal{J}-\Gamma_0)) = \operatorname{non}(\begin{bmatrix} \mathcal{I}-\Gamma_0\\ s\mathcal{J}QN_0 \end{bmatrix}) = \lambda(\mathcal{I}, \mathcal{J}).$ (2)  $\operatorname{non}(S_1(\Gamma_0, \mathcal{J}-\Gamma_0)) = \operatorname{non}(S_1(\Gamma_0^m, \mathcal{J}-\Gamma_0)) = \operatorname{non}(\begin{bmatrix} \Gamma_0\\ s\mathcal{J}ON_0 \end{bmatrix}) = \mathfrak{b}_{\mathcal{J}}.$ 

- Let  $\mathcal{I}, \mathcal{J} \subseteq \mathcal{P}(\omega)$  be ideals.
  - $\begin{array}{l} (1) \ \operatorname{non}(\operatorname{S}_1(\mathcal{I}\text{-}\Gamma_0,\mathcal{J}\text{-}\Gamma_0)) = \operatorname{non}(\operatorname{S}_1(\mathcal{I}\text{-}\Gamma_0^{\mathrm{m}},\mathcal{J}\text{-}\Gamma_0)) = \operatorname{non}(\begin{bmatrix} \mathcal{I}\text{-}\Gamma_0\\ \mathcal{s}\mathcal{J}\operatorname{QN}_0 \end{bmatrix}) = \lambda(\mathcal{I},\mathcal{J}). \\ (2) \ \operatorname{non}(\operatorname{S}_1(\Gamma_0,\mathcal{J}\text{-}\Gamma_0)) = \operatorname{non}(\operatorname{S}_1(\Gamma_0^{\mathrm{m}},\mathcal{J}\text{-}\Gamma_0)) = \operatorname{non}(\begin{bmatrix} \Gamma_0\\ \mathcal{s}\mathcal{J}\operatorname{QN}_0 \end{bmatrix}) = \mathfrak{b}_{\mathcal{J}}. \end{array}$
- If  ${\mathcal I}$  is tall then
  - (3)  $\operatorname{non}(S_1(\mathcal{I}-\Gamma,\Gamma)) = \operatorname{non}(S_1(\mathcal{I}-\Gamma_0,\Gamma_0)) = \operatorname{non}(S_1(\mathcal{I}-\Gamma_0^m,\Gamma_0)) = \operatorname{non}(\begin{bmatrix}\mathcal{I}-\Gamma_0\\QN_0\end{bmatrix}) = \min\{\operatorname{cov}^*(\mathcal{I}), \mathfrak{b}\}.$
  - (4) (A. Kwela-M. Repický)  $\operatorname{non}(\begin{bmatrix} \mathcal{I} Q N_0 \\ Q N_0 \end{bmatrix}) = \operatorname{non}(\begin{bmatrix} \mathcal{I} \Gamma_0 \\ \Gamma_0 \end{bmatrix}) = \operatorname{non}(\begin{bmatrix} \mathcal{I} \Gamma \\ \Gamma \end{bmatrix}) = \operatorname{cov}^*(\mathcal{I}).$

• Let  $\mathcal{I}, \mathcal{J} \subseteq \mathcal{P}(\omega)$  be ideals.

 $\begin{array}{ll} (1) & \operatorname{non}(\mathrm{S}_{1}(\mathcal{I}\text{-}\Gamma_{\mathbf{0}},\mathcal{J}\text{-}\Gamma_{\mathbf{0}})) = \operatorname{non}(\mathrm{S}_{1}(\mathcal{I}\text{-}\Gamma_{\mathbf{0}}^{\mathrm{m}},\mathcal{J}\text{-}\Gamma_{\mathbf{0}})) = \operatorname{non}(\begin{bmatrix} \mathcal{I}\text{-}\Gamma_{\mathbf{0}}\\ \mathfrak{s}_{\mathcal{J}}\mathrm{QN}_{\mathbf{0}}\end{bmatrix}) = \lambda(\mathcal{I},\mathcal{J}). \\ (2) & \operatorname{non}(\mathrm{S}_{1}(\Gamma_{\mathbf{0}},\mathcal{J}\text{-}\Gamma_{\mathbf{0}})) = \operatorname{non}(\mathrm{S}_{1}(\Gamma_{\mathbf{0}}^{\mathrm{m}},\mathcal{J}\text{-}\Gamma_{\mathbf{0}})) = \operatorname{non}(\begin{bmatrix} \Gamma_{\mathbf{0}}\\ \mathfrak{s}_{\mathcal{J}}\mathrm{QN}_{\mathbf{0}}\end{bmatrix}) = \mathfrak{b}_{\mathcal{J}}. \end{array}$ 

- If  ${\mathcal I}$  is tall then
  - (3)  $\operatorname{non}(S_1(\mathcal{I}-\Gamma,\Gamma)) = \operatorname{non}(S_1(\mathcal{I}-\Gamma_0,\Gamma_0)) = \operatorname{non}(S_1(\mathcal{I}-\Gamma_0^m,\Gamma_0)) = \operatorname{non}(\begin{bmatrix}\mathcal{I}-\Gamma_0\\QN_0\end{bmatrix}) = \min\{\operatorname{cov}^*(\mathcal{I}), \mathfrak{b}\}.$

 $(4) \ \ \textbf{(A. Kwela-M. Repický)} \ non(\begin{bmatrix} \mathcal{I}\mathrm{QN}_0\\ \mathrm{QN}_0 \end{bmatrix}) = non(\begin{bmatrix} \mathcal{I}\text{-}\Gamma_0\\ \Gamma_0 \end{bmatrix}) = non(\begin{bmatrix} \mathcal{I}\text{-}\Gamma\\ \Gamma \end{bmatrix}) = cov^*(\mathcal{I}).$ 

- Consistency
  - (1) If  $\mathfrak{b} = \mathfrak{c}$  then  $\operatorname{non}(S_1(\mathcal{I} \Gamma, \Gamma)) = \operatorname{cov}^*(\mathcal{I})$  for every tall ideal  $\mathcal{I}$ .
  - (2) If  $\mathfrak{b} < \mathsf{cov}^*(\mathcal{I})$  then  $\operatorname{non}(S_1(\mathcal{I}-\Gamma,\Gamma)) < \mathsf{cov}^*(\mathcal{I})$  for every tall ideal  $\mathcal{I}$ .
  - (3) If  $\mathfrak{p} = \mathfrak{b}$  then  $\operatorname{non}(S_1(\mathcal{I} \Gamma, \Gamma)) = \mathfrak{b}$ .
  - (4) If  $\operatorname{cov}^*(\mathcal{I}) < \mathfrak{b}$  then  $\operatorname{non}(S_1(\mathcal{I} \Gamma, \Gamma)) < \mathfrak{b}$ .
  - (5) If  $\mathfrak{b}_{\mathcal{J}} < \mathfrak{d}$  then  $\operatorname{non}(S_1(\mathcal{I} \Gamma, \mathcal{J} \Gamma)) < \mathfrak{d}$ .

#### Proposition (V.Š., J.Šupina)

- (1) If  $\mathfrak{p} < \mathfrak{b}$  there is an  $S_1(\Gamma, \Gamma)$ -space X such that  $C_p(X)$  is not an  $S_1(\mathcal{U}-\Gamma_0^m, \Gamma_0)$ -space.
- (2) If cov<sup>\*</sup>(I) < b there is an S<sub>1</sub>(Γ, Γ)-space X such that C<sub>p</sub>(X) is not an S<sub>1</sub>(I-Γ<sup>m</sup><sub>0</sub>, Γ<sub>0</sub>)-space.
- (3) For any b-Sierpiński set S there is an ultrafilter U such that S such that C<sub>p</sub>(S) is not an S<sub>1</sub>(U-Γ<sub>0</sub>, Γ<sub>0</sub>)-space (but S is an S<sub>1</sub>(Γ, Γ)-space).
- (4) If b < b<sub>U</sub> then there is an S<sub>1</sub>(Γ, U-Γ)-space X such that C<sub>p</sub>(X) is not an S<sub>1</sub>(Γ<sup>m</sup><sub>0</sub>, Γ<sub>0</sub>)-space.
- (5) If b<sub>J</sub> < 0 then there is an S<sub>1</sub>(Γ, Ω)-space X such that C<sub>p</sub>(X) is not an S<sub>1</sub>(Γ<sup>m</sup><sub>0</sub>, J-Γ<sub>0</sub>)-space.
- (6) If b < cov\*(I) then there is an [I-Γ, Γ] -space X such that C<sub>p</sub>(X) is not an S<sub>1</sub>(I-Γ<sup>m</sup><sub>0</sub>, Γ<sub>0</sub>)-space.

#### Conclusion



#### Diagram. The overall relations of investigated properties.

# Thank you for your attention

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